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Technical Document 307

HUMAN ENGINEERING PRINCIPLES
APPLIED TO A LABORATORY
DEVELOPMENT MODEL:
A DEMONSTRATION

J Rhode and B Simonson NOSC

ENS J Stacy, USN and B Foulke Systems Consultants Inc

22 May 1979

Prepared for Naval Electronic Systems Command Code 304

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Commander

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Technical Director

ADMINISTRATIVE INFORMATION

This report was originally prepared as a group project in partial satisfaction of requirements for a college course taken outside of Naval Ocean Systems Center.

The subject system is being developed under the sponsorship of Naval Electronic Systems Command (NAVELEX), Code 304.

The authors combined their efforts for this report because of a mutual interest in the development, and the evidence of a need for human factors engineering effort on the system.

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SIMMARY

Project.

This report presents the results of a group effort to examine the "human factors" aspects of a current Navy development. The system examined is approaching the laboratory demonstration stage in its development and therefore could be complemented by the investigations and results. A representative segment of the laboratory model system was used as the basis for this project.

Results.

The examination was done in terms of (a) the information to be passed by the electronic system to the human users and (b) the way by which technicians, as operators, would make use of the system (controls and displays).

Perhaps the most significant and yet most difficult to quantify are the results of part (a). Table 1 shows a comparison of the information seen to be required from the system, as perceived by Navy personnel, with the perceptions of the system designers. The differences can appear to be slight and vastly separated at the same time.

Control and display examinations were more to the point and easily defined. Suggestions and proposals for both areas are made herein.

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Table 1.

Comparison Of User Defined vs. Designer Defined Information Requirements

Defined By Navy	Defined by System Designers
Information Flow (Fig. 4, Solid Lines)	Information Flow (Fig. 4, Dashed Lines)
Three (3) Hierarchical Levels, Lowest with two (2) Subdivisions	Three (3) Hierarchical Levels, Excluding Operations Level
Commander Requires Status (System, Subsystem), Estimated Time to Repair (ETR), Equip- ment Name	Commander and Comm. Officer Require System Status, ETR
Commander Requires System Status Defined M1-M4	Commander Requires System Status (Good, Marginal, Bad)
Command, OPS, and Equipment Level Require Subsystem Status Defined C1-C4	Communications Officer Requires Subsystem Status (Good, Marginal, Bad)
Command and Equip. Level Requires Equipment Name (for Faulty Subsystem)	Maintenance Requires Equip- ment Name (for Faulty Sub- system)
Commander Requires Supply System Status for Equipment Under Repair	Maintenance Requires Supply System Status for Equipment Under Repair
Maintenance and Supervisory Technicians Require Test Measurement Information	Same

Recommendations.

The project has illustrated to both Navy personnel and system engineers, that developmental systems can have some definite benefits from serious human engineering inputs. A general recommendation is that such inputs be a part of the development process, and that in the case covered by this report, the detailed recommendations of Section IV be incorporated.

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I. INTRODUCTION

1. Background.

a. General.

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An electronic, microprocessor-controlled monitoring system is being developed for the Navy. Its purpose is to provide performance measurement information to shipboard personnel concerning the operation of a variety of ship systems (called Base Systems). The information provided is to be used by maintenance personnel in the testing and repairing of Base Systems equipment, and by Command personnel in the assessment of Base Systems status (good, marginal, bad).

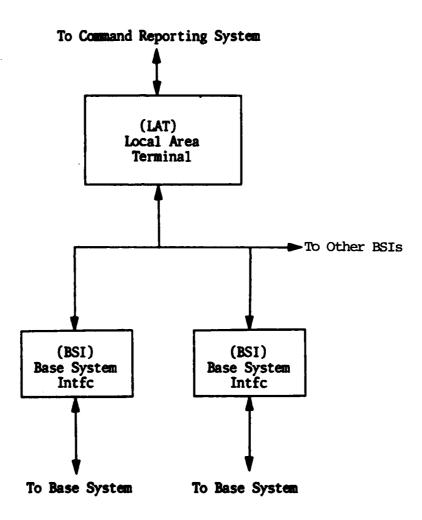
The monitor system will be situated in equipment areas, such as the radio room, aboard ship. It is comprised of two major elements with a suitable connection link between them. (See Fig. 1). The first element is the Base system Interface (BSI) which is connected directly to the Base System equipment and is operated by maintenance technicians in the performance of test and measurement duties. A variety of BSI units may exist in a given equipment area, depending upon the variety of equipment types. Each BSI will monitor all of the equipments of a particular type in any one equipment space.

The BSI is controlled by, and communicates test results to, the second element called the Local Area Terminal (LAT). Control signals and data signals between the BSI and LAT are carried by the connecting link. There will normally be one LAT in each equipment area, although an equipment area could consist of more than one compartment of the ship.

Operators of the Local Area Terminal will either be supervisory
maintenance personnel or maintenance technicians. The LAT is the controlling

Figure 1.

Equipment Area Monitor System



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element for all of the BSI units connected to it, and it has access to all of the monitor information about the Base Systems.

The LAT will send status data, derived from the BSI measurement information, to Command personnel via an undefined system called the Command Reporting System. (See Fig.2).

b. Laboratory demonstration model.

Communications equipments have been chosen as the intial equipments to be monitored. A test configuration of a monitor system for selected communications equipment has been designed and is being developed for laboratory demonstration purposes. It will consist of two BSI units, of which one monitors a high frequency (HF) receiver type, and the other monitors an ultra-high frequency (UHF) transceiver type. Also included in the demonstration model is a Local Area Terminal. These components of a Communications Monitor System and the information they deal with are the subject areas of this report. (See Fig.3)

2. Purpose of the project.

The purpose of this project is to evaluate the human factors aspects of the design of a Communications Monitor System. This evaluation consists of two parts:

- a. The types and amounts of information required to provide the status indication and maintenance measurement functions.
- b. The displays and controls to be used by maintenance and supervisory personnel during the operation of the BSI units and the LAT.

3. Scope of the project.

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The Communications Monitor System laboratory model will include more

Figure 2.

Command Reporting System (Connected To LAT)

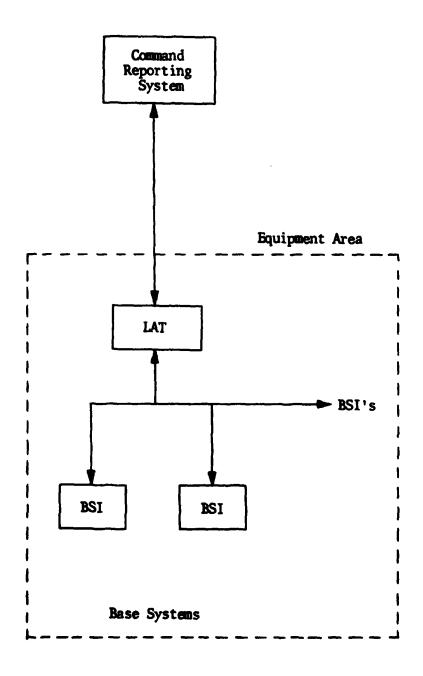
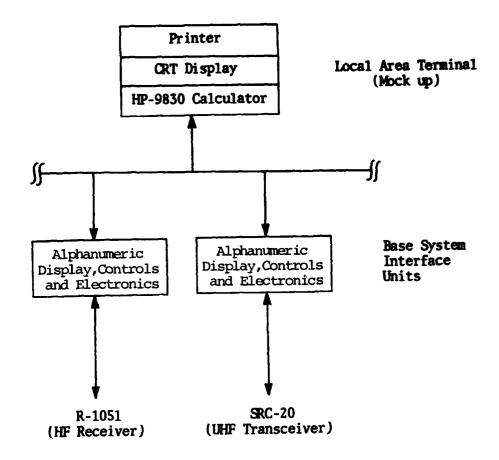


Figure 3.

Communications Monitor System (Laboratory Demonstration Model)



equipment than is described above. The description given is that of the portion chosen as a suitable class project and as such defines the scope of the project. The points of the evaluation are itemized below:

- a. Information requirements.
 - (1) Status (command)
 - (2) Maintenance (technicians)
- b. Controls and displays.
 - (1) Local Area Terminal (supervisory technicians)
 - (2) Base Systems Interface for HF receivers (technicians)
 - (3) Base System Interface for UHF transceivers (technicians)

II. PROCEDURE

1. User requirements study.

Investigations were made into the requirements for information about communications systems by shipboard personnel. Interviews were conducted with active Navy personnel of both Command and Maintenance types. Documents which indicate information requirements were studied. These are maintenance check-off lists for technicians and operational procedures documents for commanders. Interviews and discussions were held with the monitor system designers to determine concepts of user requirements to which the system was originally designed. The results of these two investigations were compared for differences affecting the operation or configuration of the monitor system. Consideration was given to the manner in which the system should be operated, and to the types of personnel who would be operators.

The results of the investigations, comparisons, and examinations are

described and tabulated in Section III. A development of the effort which concerns the automatic production of certain maintenance and logistics forms is included as Appendix A.

2. Control and display evaluation.

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1.3.

a. General.

Each of the BSI units included in this project (HF receiver and UHF transceiver) has an operator control panel design which will be used in the laboratory model. The two completed designs were evaluated against MIL-STD-1472B and other human factors design publications. The evaluation studies were performed with consideration of the manner in which the monitor system is intended to be operated, as determined during investigations of paragraph 1 of this Section. The LAT operator control panel was designed new for this project using the same information and publications as used for the BSI control panel evaluations. The results of the evaluations and design, including diagrams of the control panels are given in paragraph 2 of Section III.

b. Procedure for Evaluating and Designing Controls and Displays.

The basic procedure used to evaluate and design the controls and displays was as follows:

- 1. Determine the information flow and information display requirements based on the results of the user requirements study.
- 2. Establish the functions to be performed by the operators and by the equipment at each position.
- 3. Determine the actions to be taken and the controls to be used by the operators.

- 4. Determine the characteristics of the planned operators.
- 5. Establish the operating environment (lighting, background noise, etc) for the equipment.
- 6. Review military standards on human engineering design criteria and technical books on human factors design criteria related to the design of the controls and displays.
 - 7. Design the controls and displays for LAT.
- 8. Prepare check-off lists for comparing the designs with documented standards, and complete the lists by evaluating the designs against each criterion on the list. Revise the design if appropriate.
- 9. Establish operating procedures for using the displays and controls, and evaluate the compatibility of the designs with these procedures in terms of providing a controls and displays layout that provides for efficient operation with a minimal probability of error.

The procedure did not include experiments. Recommendations about the possible use of experiments are provided in Section IV.

III. RESULTS

1. <u>User requirements study</u>.

a. General.

The user requirements (types and amounts of information) investigated were of two general classifications:

-as perceived by potential system users (Navy Command and Technician personnel)

-as perceived by original system designers.

Data were gathered by interviews with a small number of personnel from active

duty Navy and from personnel engaged in design and demonstration of the Monitor System. The determinations made and reported here are subject to much refinement because of the presence of opinion and conjecture.

The general flow of information with regard to communications equipment is shown in Figure 4, solid lines. This flow passes through three defined hierarchical levels (Ref.6), ultimately arriving at the Commanding Officer (CO). A summary of user requirements has been presented in Table 1 on the Summary page, and is repeated here.

b. Command requirements.

Information required at the Command level regarding communications spans a wider range of detail than thought by the designers of the monitor system. The requirement for information is a function of the operability of the communications system. As the operability decreases, the need for detailed information increases, culminating in an abiding interest in the estimated time to repair, status of the supply system (for the particular repair), and the name of the equipment at fault. Designers had considered that system status (good, marginal, bad) and estimated time to restore were good and sufficient information. Additionally, the requirement for logistics and supply information extends into Command levels to an extent not considered by original designers. More detailed information is presented on this subject in Appendix A.

The highest level of refined information (system status) required by Command is defined as MI through M4, in descending order of system operability. The characteristics which define each of the levels are presented as a flow diagram, Figure 5. Requirements for lower level information develop when the above status indications show degradation of capabilities. The lower levels of information are discussed in the following paragraphs.

Figure 4.

Hierarchical Information Flow For Communications Systems.

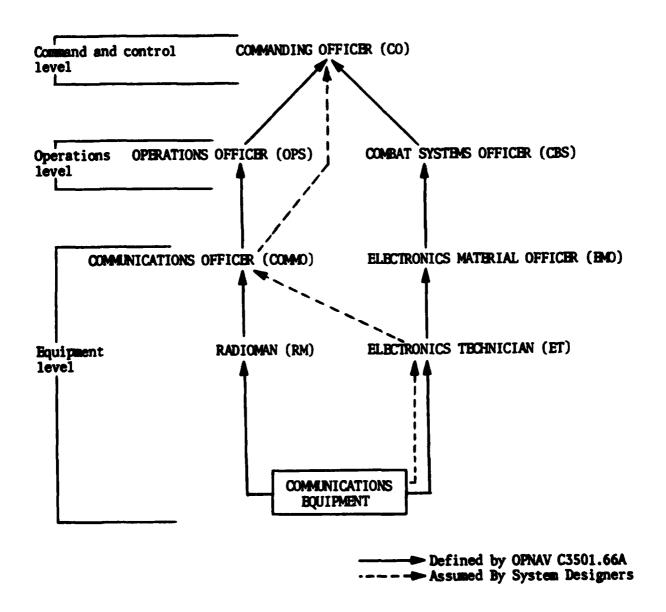


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Commander Requires Supply System Status for Equipment Under Repair	Maintenance Requires Supply System Status for Equipment Under Repair
Maintenance and Supervisory Technicians Require Test Measurement Information	Same

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Figure 5.

M1--M4 Decision Flow Diagram

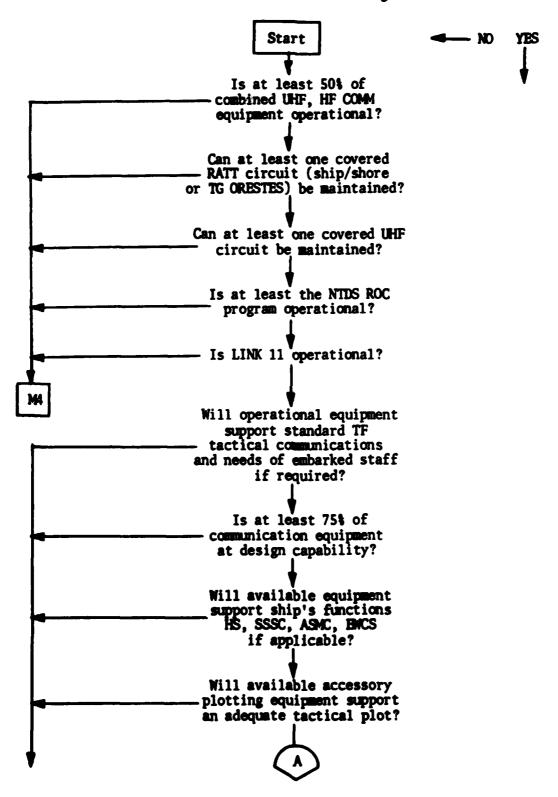
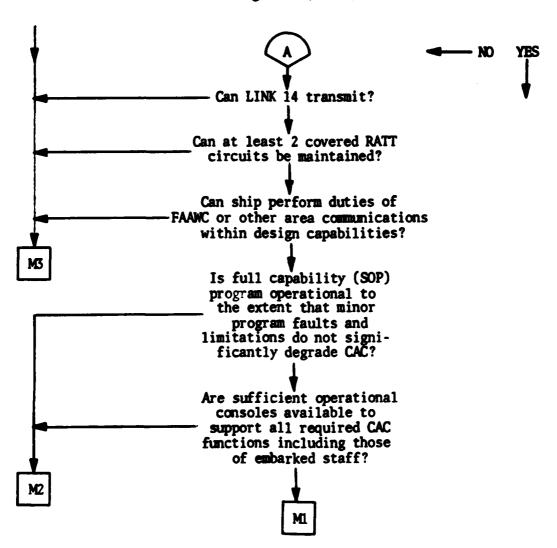


Figure 5 (cont.)



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c. Operations requirements.

The Operations level is an intermediate level more related to Command than to Maintenance. Original designers of the monitoring system had not considered the level directly; rather, they had supposed the technician's watch supervisors (thought to be Communications Officers) to be an intermediate level for the flow of information. Reference 6 shows that while the idea is correct, the essentials are missing and the flow is from Communications Officer to Operations Officer to Communications Officer (Fig. 4). The Communications Officer is a member of the first level (equipment level).

The highest level of system status information required at the Operations level (Operations Officer) is defined as C1 through C4. Each major equipment group will have a definitive set of considerations which indicate the level of operability (C1 - C4) for the equipment group. Thus, HF communications will have one, Satellite communications (SATCOM) will have another, UHF communications will have still another, and so forth. The monitor system under study herein has BSI units for HF and UHF communications, and the criteria for establishing conditions C1 - C4 for them is classified, but can be found in COMNAVSURFPACINST 3501.3, Readiness Reporting Guide (Ref. 12).

d. Maintenance requirements.

The maintenance level (equipment level) is the lowest level in the hierarchy and requires the most detailed technical information.

Technicians are required to perform a variety of measurements, usually on a periodic basis, which are designed to ensure equipment operability. The system in use is the Planned Maintenance System (PMS) and the information required by technicians is delineated by Maintenance Requirement Cards (MRC) (Ref. 5). An example MRC is reproduced as Figure 6. This card is one of a group related to PMS on HF receivers and indicates three tests which are

Figure 6.

Maintenance Requirement Card for HF Receiver Sensitivity Test

MAP BYSTEM	SUBSYSTEM	MAC COOK	_
Combat		C-193 W-	ı
SVSTEM	AN/SRC-20,20A Radio Set	RM3 0.0	
MANUFACTOR RECOGNISMS OF SCREEN		 	
1. Test operate radio s	et.	TOTAL MAN	
1. Forces afloat comply Precautions for Forceseries.	with Navy Safety es Afloat, OPNAVINST 5	0.4	
1. Handset 2. Dummy Load, DA-412/U 4683) 3. Test cable, RG-213/U type C male connecto one end and type N m connector on other e	(SCAT with r on ale		,
(1) TEST KEY to 0 (2) EXCITATION to (3) LOCAL-REMOTE (4) RF POWER OUTP (5) POWER to POWE b. Set AN/URC-9() s' (1) CHAN SEL to R (2) MODE to TONE (3) SQUELCH to OF (4) POWER to ON (5) DIMMER fully c. Set Radio Set Con: (1) EMERGENCY POW (2) LOCAL-REMOTE d. Disconnect antenn e. Connect dummy loaf. Connect thandset to 1. Test Operate Radio Sea. Momentarily press indicators on rad 9() should light radio set control b. Allow a 5-minute c. Set AN/URC-9() N	AUTO to LOCAL UT to HIGH R witches and controls: EMOTE PRESET F clockwise trol C-3866/SRC switche ER to POWER to LOCAL a cable from RF amplif d to RF amplifier ANT o AN/URC-9. at. RADIO SET POWER START io set control, RF amp t; EMERGENCY POWER ind: should light. warmup. ETER switch successive.	es and controls: ier ANT jack. jack. button; POWER lifier and AN/URC- lcator lamp on	PMGR 1 OF 3 C6
following position position. (1) +325V (2) +125V	ns; meter should indica		e in
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MAINTENANCE REQUIREMENT CARD (MRC)

performed by the technician. The test made by the BSI effectively makes the three tests in one measurement, under controlled conditions, called "noise figure test." This measurement is also displayed as "receiver sensitivity."

e. Monitor system operators.

The LAT and BSI units of the monitor system will be operated by technicians from maintenance divisions (ET rate, electronic technician). The BSI will be operated by ET2 or ET3 level personnel, and the LAT, a supervisory position, will be operated by ET1 or ETC. The refined information, status, estimated time to repair, supply status, etc., will be forwarded to the Command Reporting System. The Communications Officer or Electronics Material Officer, as an organizational supervisor, is likely to make use of the LAT in the case of a less than perfect system status indication (C2 through C4). The Operations or Combat System Officer and the Commanding Officer, which represent the next two higher levels of information flow, will be primary users of the Command Reporting System (CRS).

2. Control and display design.

a. LAT design.

The basic functions performed at the LAT are:

- (1) Acquire and maintain information on the status of all BSI units connected to it.
- (2) Assign tasks for maintenance of these BSI units and supervise the task performance.
 - (3) Report status information to Command personnel.
 The functions requires the completion of various to

Performance of the functions requires the completion of various tasks, some of which will be accomplished by equipment and others by personnel. The design for the LAT controls and displays depends on which tasks will be allocated to

operators and which to equipment. This allocation is based upon a consideration of which types of things are done best by people and which by machines, and is a major input to the system design. The system design will determine the man-to-man, man-to-machine, and machine-to-machine interfaces. A block diagram showing these interfaces for the monitoring system is provided in Figure 7. The specific tasks to be performed at the LAT are listed in Table 2.

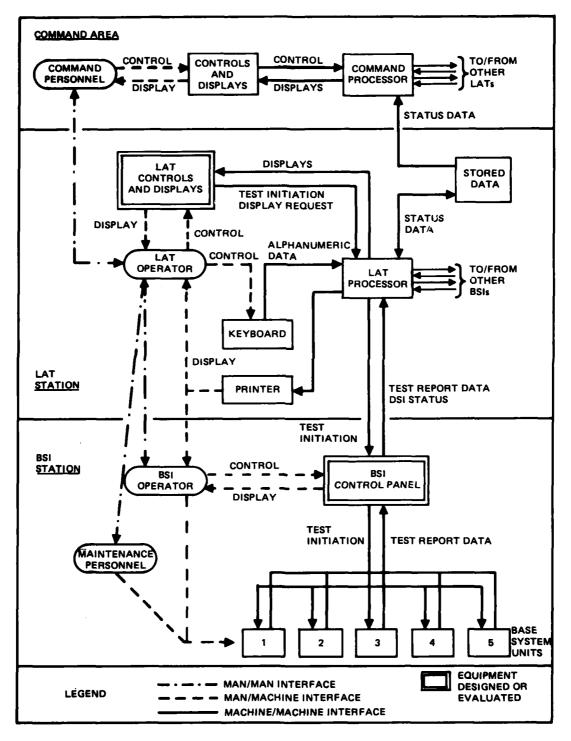
A design for the LAT controls and displays has been completed. The design consists of a cathode-ray-tube (CRT) display device and an eight-button function key control device. These are shown in Figure 8. Design of the keyboard for alphanumeric entry of information about supply status, operational capabilities (Fig. 5), or problems associated with repairing equipment is beyond the scope of this project.

The specific control actions that the LAT operator would need to take were determined and grouped into ten sets of eight or fewer actions per set. This grouping enables the control devices to be a simple bank of eight function keys. These keys will be positioned directly below a CRT that will display the LAT information. The CRT display is divided into three areas as shown in Figure 8. The functions to be performed when the operator presses a function key will depend on the selected function key action set. The LAT action set display shown in Figure 8 is divided into eight sections located directly above the eight keys. Each section indicates the function which will be performed when the corresponding key is pressed. The formats for this display are shown in Figure 9. The top portion of the CRT display shows the current overall status of the Base System equipment and the current status of the monitoring system. These displays provide a quick overview of the current situation and are continually updated to present the most current

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Figure 7.

Block Diagram of Monitor System Interfaces



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Table 2. LAT Task Allocation

No	Task Description	Allocated To
1	Initiate tests to obtain BSI unit status data and data on the performance of the monitor system	a) Equipment, to accomplish automatically when first starting the monitor action and periodically thereafter
		 b) Operator, to accomplish when needed due to a particular situation
2	Establish the rate of per- iodical automatic status testing	Operator
3	Direct BSI Station Equipment to perform unit testing	Equipment
4	Receive BSI unit status Information from BSIs	Equipment
5	Maintain records of BSI unit status data	Equi pment
6	Determine what testing to perform in special situations	Operator
7	Provide information to the operator for evaluation and decision making	Equipment
8	Provide status information to command personnel	a) Equipment, for information received from BSIs or entered into storage by keyboard
		b) Operator, for evaluations and estimates not part of stored data

No.

Table 2. (cont.)

71		Γ Τ
9	Respond to directions from command personnel	Operator
10	Keep informed about BSI unit status to enable making maintenance decisions	Operator
11	Direct maintenance personnel to perform specific tasks	Operator
12	Obtain and evaluate informal information from maintenance personnel	Operator
13	Supervise performance of maintenance personnel	Operator

Figure 8.
LAT Display and Control Console

Current Condition Display
Status Information Display
LAT Action Set Displays

Figure 9. LAT Action Set Displays

	Performance Checks on Monitor System Operation						
NEXT SET	LAT SELF	BSI 1 INTER	BSI 1 SELF	BSI 2 INTER	BSI 2 SELF	BSI 3 INTER	BSI 3 SELF
		Change 1	lime For P	eriodic l	lnit Testi	ng	
NEXT SET	NORMAL PERIOD	BSI 1 30 MIN	BSI 1 1 HR	BSI 2 30 MIN	BSI 2 1 HR	BSI 3 30 MIN	BSI 3 1 HR
ļ		Ini	tiate BSI	1 R-105	1 Tests		
NEXT SET	R-1051 (1)	R-1051 (2)	R-1051 (3)	R-1051 (4)	R-1051 (5)	R-1051 (6)	R-1051 (7)
		Initi	ate BSI 2	SRC-200	N) Tests		
NEXT SET	ALL SRC-20		ALL TESTS	RCVR SENS	POWER OUTPUT	MODU- LATION	VSWR
<u></u>		Obta	in Summar	y Status	Displays		
NEXT SET	ALL UNITS		PROBLEM UNITS		UPDATE NEEDED	LOCKED	HARD COPY
		Obt	tain BSI U	hit Test	Reports		
NEXT SET	BSI 1 UNITS		BSI 2 UNITS		BSI 3 UNITS		HARD COPY

information. They are presented at the top of the display area and separated from the other display information so that they will stand out, since they alert the LAT operator to situations which may need his special attention. None of the alerts were so time critical as to warrant the use of flashing lights or audio signals. A proposed format for this display is shown in Figure 10. The group at the left of this display shows the most critical factors about the monitored equipment. The overall condition code (C1, C2, C3, C4) indicates the level of capability of the monitored equipment. The other two status items are simply the number of Base Equipment units that are experiencing problems (failures, no status information available, etc.) and the number of units for which updated status information is needed shortly or the units will be considered problem units. The group at the right of the display indicates whether the different monitor system performance areas are OK or BAD. These indicators were chosen rather than others such as GO and NO-GO which would infer that the indicated status pertains to the ships operational condition. The status indicated by OK or BAD is simply whether the monitor system is operating correctly, not whether the operational equipment is operating correctly.

Descriptions of other displays that will be presented to the operator are provided in Appendix B.

b. BSI (R-1051).

The existing design for the BSI (R-1051) control panel (Figure 11) has been evaluated. Several changes are suggested in order to improve the design from the human factors aspect. The changes are shown in Figure 12, and are discussed below:

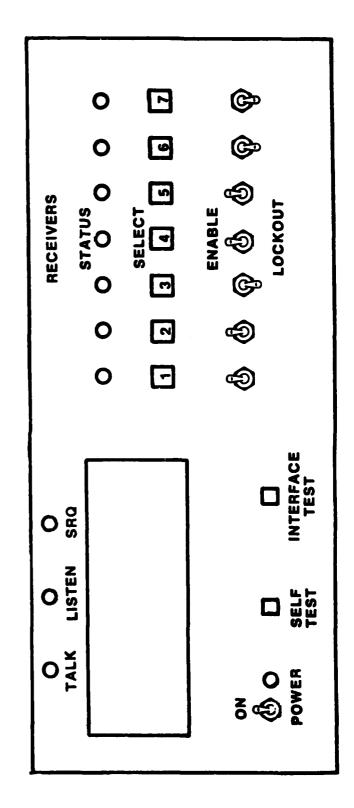
Figure 10. Current Condition Display

REQ UPDATE	5
PROBLEM	4
OVERALL	C-2

3 SELF	8
RSI 3 INTFC SEL	BAD
2 SELF	8
BSI 2 INTFC SE	ğ
1 SELF	¥
BSI INTFC	ĕ
LAT STATUS	æ

Figure 11.

Evaluated Design for Panel of BSI for R-1051



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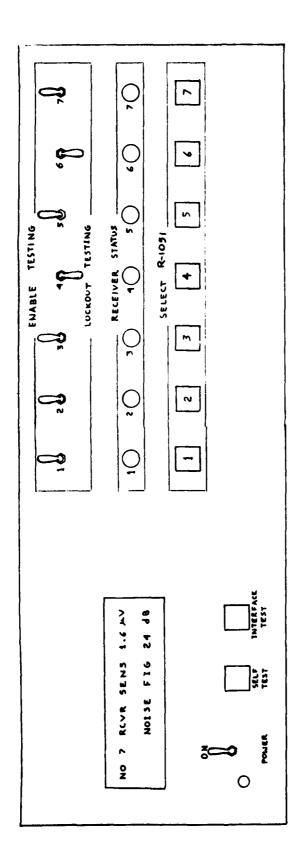


Figure 12.
Proposed Redesign for Panel of
BSI for R-1051

TO SERVICE OF THE SER

- (1) Remove the TALK, LISTEN, and SRQ display lights since they do not present information pertinent to the operation of the panel or results of the testing.
- (2) Relocate the ENABLE, LOCKOUT toggle switches to the top of the panel so that the operator's hand does not obstruct his view of these switches while he is selecting the unit to be tested. This relocation places the indication of whether or not testing of a unit is "locked out" near the status light for that unit. If the operator inadvertently attempts to test a "locked out" unit and sees no indiction of the test results on the status light, he will easily notice that testing is "locked out".
- (3) Keep the functional grouping of control and displays, but clearly indicate the functional boundaries and provide more precise labels for the functional areas.
- (4) Provide a number label for each toggle switch and status light to indicate with which receiver they are associated. Furthermore, although it cannot be done on the panel, the operator must be provided with information to determine which actual physical unit corresponds to receiver number 1, 2, 3, etc.
- (5) Place labels indicating particular tests to be performed on the test control pushbuttons where possible.
- (6) Provide standardization among BSIs of control and display positioning.
- (7) Provide 1.25" instead of 1.00" separation between the centers of the toggle switches, status indicator lights and unit selector push buttons. This will reduce the risk of inadvertently bumping and possibly actuating an adjacent control. The separation distances are slightly above the recommended minimums in McCormick (Ref. 7), Figure 11-14.

- (8) Specify that toggle switches are 1/8 inch wide at the tip, 0.7 inches long and require a displacement of 50 degrees and force of 20 oz to operate, pushbuttons are 0.5 inches square and require a displacement of 3/16 inch and a force of 20 oz to activate. These characteristics meet the requirements of McCormick (Ref. 7) Appendix B, Table B-2.
- (9) Place the POWER ON indicator light to the left of the power on/off switch so that it is not associated with the SELF TEST pushbutton.
- (10) Specify that status lights are three-color; red for failure, yellow for pass but marginal, and green for good, and that the lights are 3/8 inch in diameter.
- (11) Reduce abbreviations to a minimum and use abbreviations in accordance with MIL-STD-12C.

The use and lighting conditions which are relevant to the panel design are listed below:

- (1) The panel will be in a standard equipment rack in a shipboard equipment area.
- (2) Operators will be trained maintenance technicians meeting physical and mental requirements for Navy enlisted personnel.
- (3) The mid-point of the panel will be between 44 and 54 inches from the floor.
- (4) Operators may be required to write test results' numerical values on blank forms. Therefore, the measured values, such as power output, will be displayed for at least 15 seconds. When a test is inadvertently attempted on a unit that has testing locked out, the test result readout will be of the form 'NO. 3 LOCKED OUT' so feedback to the operator is always provided.
- (5) Operators will operate the panel from a distance no greater than arm's reach (approximately 20 inches).

- (6) Room lighting will be the normal shipboard equipment area white lights. Panel illumination will be above 1 ft-L.
 - (7) Panel surfaces will have a flat finish to reduce glare.
 - (8) The normal sequence of operations is as follows:
 - a. Set the toggle switches to ENABLE or LOCKOUT testing.
- b. Perform "self test" and "interface test." Check the readout after each test.
 - c. Select the test(s) to be performed (BSI SRC-20 only).
 - d. Select the unit(s) to be tested.
 - e. Check the unit status (status lights).
- f. If the status light does not light, check the toggle switch setting to see if testing of that unit has been locked out.
- g. If the status light is not green, record the reported value on the appropriate form.
- h. If more than one test and/or more than one unit has been selected, repeat items e, f, and g.
 - i. When additional testing is required, repeat items c through h.Specific characteristics of the test results readout are as follows:
- (1) The readout will be constructed from ten Hewlett-Packard four-character solid state alphanumeric display components. These components will be arranged to provide two rows of 20 characters as shown in Figure 12. The characters are formed with a 5 by 7 dot matrix using light-emitting diodes (LED's).
- (2) The width and height of capital letters and numbers are 0.105 and 0.146 inches respectively except for the letter I and number 1. I and 1 are both 0.063 by 0.146 inches.
 - (3) The color of the characters is red.

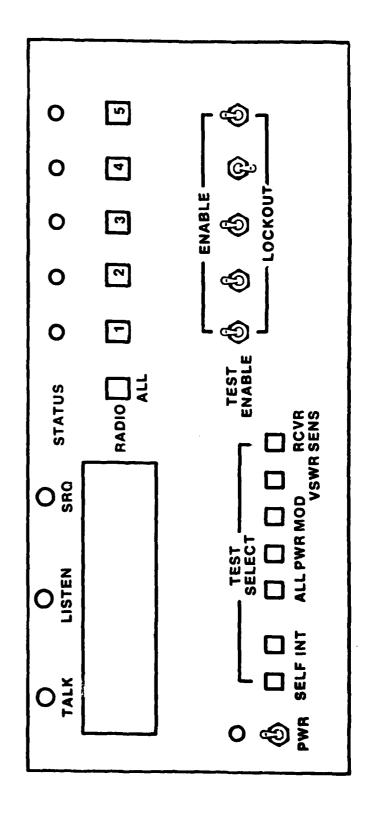
(4) Additional information, including the configuration of all 128 characters, is provided in Appendix C. This readout has been operated and informally evaluated by various subjects. Their subjective feelings are that the characters are very readable at the distances occurring in normal operation. When asked to estimate the height of the characters, most subjects reply with a value of approximately 1/4 inch rather than the actual height (0.146 inches). Also, the sample readout shown in Figure 12 is actual size and these characters seem to be quite readable from 20 inches. Furthermore, the character heights meet the requirement of 0.090 inches for a viewing distance of 20 inches or less, with an illumination level above 1 ft-L as specified in MIL-STD-1472B, paragraph 5.5.5.13. Experiments could be conducted relatively easily and would determine if the readouts are indeed acceptable. It is suggested that a group of 15 to 20 subjects be tested to determine the accuracy with which the readout can be read at 20 and at 30 inches. An error would consist of perceiving a wrong unit number, measured parameter (modulation etc.), or reported value (24 dB, etc.). A criterion of acceptable percentage of errors would have to be established based on the criticality of making an error. If the results prove to be inconclusive, further testing could be performed.

c. BSI (SRC-20).

The existing design for the BSI (SRC-20) control panel, presented in Figure 13, has been evaluated. As with the other BSI control panel, several changes are suggested. The changes are incorporated into the proposed panel design shown in Figure 14. Most of the changes are the same as those proposed for the BSI (R-1051). The use and lighting conditions for both BSI's will be the same, and the proposed designs are nearly the same.

Figure 13.

Evaluated Design for Panel of BSI for SRC-20



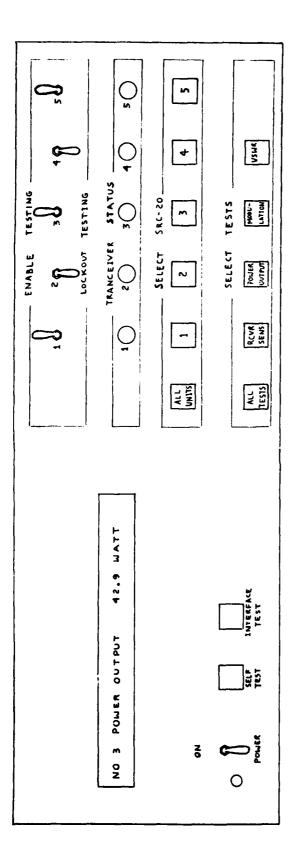


Figure 14.
Proposed Redesign for Panel of BSI for SRC-20

There are three differences in the designs. First, the test results readout will be one row with 32 characters, and it will display the measured value of a given parameter for a specific unit. Second, there are only 5 different units to be tested. The third difference results from the fact that the operator can elect to run any combination (or all) of four different tests on a specific unit or on all units. This capability is provided by adding a set of pushbuttons to select the test(s) as shown in Figure 14, and by including a pushbutton to select all units.

The layouts of the controls and displays for the proposed designs of both BSI panels are based on the sequence of operations described in paragraph 2.b BSI (R-1051). The primary considerations for the layouts are to arrange controls and displays to:

- (1) Minimize the lengths of links that are most frequently used by considering the normal operational sequence.
- (2) Minimize the interference between operating the controls and viewing the displays.
 - (3) Maximize the standardization of panel layouts.
 - (4) Group controls and displays according to functions.
 - (5) Maximize simplicity of the layout.

The panel labeling is shown in actual size in Figures 12 and 14. The minimum character height is 0.12 inches, and as stated in paragraph III 2.b, the panel illumination will be above 1 ft-L. This size meets the requirements as specified in MIL-STD-1472B, Table X for noncritical identification labels. To assure that the other requirements of MIL-STD-1472B have been met by the controls and displays of the LAT and both BSI's, a check-off list has been completed. This list is shown in Appendix D. For the most part, abbreviations have been avoided in both the panel labeling and display

readout. The abbreviations used are listed below, and are in accordance with MIL-STD-12C (applicable pages shown in Appendix E).

Labels	RCVR	for receiver
	SENS	for sensitivity
	VSWR	for voltage standing wave ratio
Readout	NO	for number

Display FIG for figure

Some other abreviations may be used for parameter units, such as dB for decibel or μ V for microvolt, but these will always be standard technical abbreviations. All abbreviations will be completely defined in users' manuals and training materials.

IV. CONCLUSIONS AND RECOMMENDATIONS

1. Conclusions.

a. User requirements.

The requirements for system status and technical information by the various organizational levels of Navy ship's crews are established by official instruction, operational activity (mission), operational readiness, individual preferences, and other factors. Each of these usually interacts with some or all of the others, as indicated in Section III.

Some of the information is defined in detail, some is highly technical and some extremely tedious. The proposed Shipboard Monitoring System appears to

have a potentially significant role in the streamlining of information flow and the relief of some of the tedium.

b. Controls and displays.

Two operator control panels (for BSI units) were evaluated for human factors and a third was designed for the first time (LAT). The evaluated units were found to have a few undesirable aspects and were redesigned with improvements. The LAT control panel design is proposed to the system designers to be included in their laboratory model of the monitoring system.

2. Recommendations.

a. User requirements study.

The large variability of the kinds and distribution of system status information, as suggested above, indicates a need for system designers to incorporate a thorough investigation into the subject. The needs of the Navy shipboard organization are documented, and the personnel are willing to indicate problems and areas of difficulty in existing systems.

It is recommended that the designers of the Shipboard Monitoring System:

- (1) Research the subject of information flow, as suggested in this report, to clarify their concepts of the utilization of such systems.
- (2) Identify existing systems which will be impacted by the development of such a system (e.g. NAVFORSTAT, PMS, etc.) for the purposes of solving old problems and avoiding the creating of new problems for shipboard personnel.

b. Controls and displays.

The redesigned BSI control panels, and the proposed design for the LAT control panel have been described in Section III, paragraph 2. The recommendation is that the system designers use these panels for their laboratory model.

As continued investigation into the human factors of the Shipboard Monitoring System design, three types of experiments and testing of components are suggested:

(1) Readout devices (BSI).

Several types of alphanumeric readout devices are available which would perform the required display function for the BSI. Among these are units using the following listed technologies:

- (a) light emitting diodes (LED)
- (b) plasma discharge displays
- (c) liquid crystal
- (d) vacuum fluorescent

Because some of these technologies have been introduced recently and are still being developed and changed, useful human factors information which could be used in the selection of a particular display unit for the BSI is not readily available. For this reason a series of tests should be conducted to aid in this selection process using subjects which match characteristics of potential users. Candidate display units should be selected and operated in environments which approximate those in which the various BSI units will be operating aboard ship. Tests should then be conducted to determine if a single display type can be selected to function optimally in all anticipated environments. In addition, special tests may be required to fully evaluate each display type. For example, Riley (Ref. 13) reports that multiple imaging as a function of vibration and refresh rates can occur. No investigation or testing was done on this subject, but such effort is recommended because of

known vibration problems aboard Navy ships.

(2) Variable function keys (LAT).

Operator entry to the LAT is by means of the eight button function key control device shown in Figure 8. The function of a particular key is determined and controlled by the LAT as a function of system operation.

Labels for the function keys are located immediately above the buttons on the CRT display device. Tests should be conducted to:

- (a) evaluate the use of variable function keys vs a much larger number of dedicated function keys.
- (b) determine the optimum location and orientation of the function keys relative to the location of the labels on the CRT device.
- (c) determine the optimum location and character font for the key labels for avoiding confusion with other LAT display information.
 - (3) System level testing and evaluation.

Testing and evaluation (T and E) of the monitor system will consist of the following parts:

- (a) Laboratory testing and redesign of breadboard unit by design engineers
- (b) Shipboard testing of advanced development model conducted by system designers with assistance of ship's personnel
- (c) Shipboard testing of engineering development model conducted by Navy testing organization (OPTEVFOR). Each stage of testing must be concerned with testing, evaluating, and optimizing human factors aspects of the design and application of the monitor system, in order to ensure a suitable development.

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APPENDIX A

User Requirements.

The typical Commanding Officer of a U. S. Navy ship wants to know as much as possible about the status of his ship even though he may not ultimately understand or "need to know" all the information he requests. This is partly because he is completely responsible for the ship, its equipment, and the lives of all personnel on board, and partly because of the inquisitiveness of the human being. However, the information required by Command level personnel, such as the Commanding Officer and Department Heads, differs in content and format from that required by shipboard maintenance personnel.

The maintenance information initially comes from the BSI and is directly usable only in conjunction with the applicable MRC (Maintenance Requirement Card) and Technical Manual. This data need only go as far as the LAT with the provision that it be stored for a specified period of time. Additional data must be already stored in the LAT in the form of subroutines or can be key entered by the operator. The amount of information presented at the CRS (Command Reporting System) is subject to close scruitiny, for if the system does not circumvent today's communications problems within the ship's chain of command it is useless at best. Since the information at the BSI and LAT is already delineated, it remains only to look at the CRS organization for information content.

The information presented and gathered should be, if possible, mostly from reporting systems that already exist. This is possible because the Navy has well-defined information systems in use and it remains only to automate this information, since it is familiar to everyone in the chain of command.

The information needed at the highest levels of Command and Control is

presented in the NAVFORSTAT CASREP System and PMS/MDS Systems. The Casualty Report (CASREP) is the expeditious means of reporting the status of a ship experiencing a diminished combat readiness posture. It serves to advise the operational chain of command of personnel and/or equipment/material conditions limiting operational readiness and also alerts logistical commands to the situation. CASREPS are not a substitute for, but are in addition to, and complement the 3-M (PMS and MDS) data. Because of the timeliness of CASREP information it is used in conjunction with NAVFORSTAT data to evaluate the combat readiness of Naval forces. It further alerts maintenance and material managers to significant problems and thus not only initiates the actions necessary to resolve the immediate casualty but also promotes detailed analysis of 3-M and related data in an effort to prevent recurrence. Regular 3-M reports are required even though CASREPS have been submitted. Since a CASREP reports only the casualty status of equipment/material, it is not a substitute for reporting in the NAVFORSTAT system. CASREPS are coded using the readiness rating codes of C2, C3, and C4 which have as a basis the mission area M1, M2, M3, and M4 ratings in the NAVPORSTAT. The 2-Kilo (Figure A-1) and 1250 (Figure A-2) forms are also tied into this system. The ship's maintenance action form (2-Kilo) is utilized as a request and documentation form for ship's force or shore based maintenance. The 1250 document lists information required to requisition a part from the supply system.

All of these reporting/documentation systems utilize the same basic information and therefore lend themselves to use in the Command Reporting System.

The first level of reporting comes from the "M" readiness ratings of the NAVFORSTAT. This details the overall readiness according to a general breakdown of ship mission areas. Command Control and Communications (CCC)

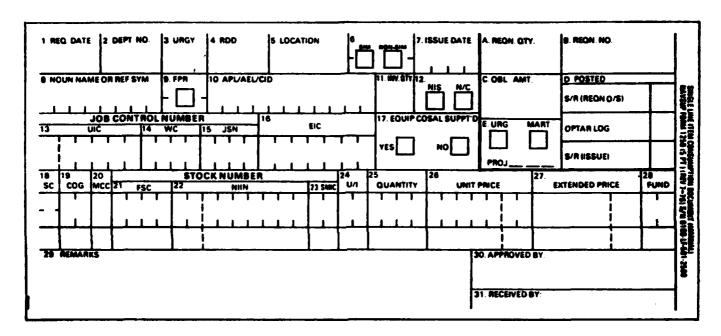
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Figure A-2

Example Form: NAVSUP 1250



covers the entire spectrum of equipment and is adequate for initial reporting. The criteria for determining the rating are found in Figure 5.

Additional criteria are classified but can be found as referenced in Table A-1. Information key-entered and retrieved from storage at the LAT, Table A-2, can be used to print out documents 2-Kilo, 1250 and CASREP messages with minimum operator interface. Subroutines can be developed to provide this information by the use of a simple matrix, LAT operator interface and the maintenance information generated at the BSI, Table A-3. This level of information is of little consequence to Command and it is used for indication of equipment performance and proper selection of the PMS (Planned Maintenance System) MRC (Maintenance Requirement Card) and technical manual for trouble—shooting the inoperative equipment.

Table A-1 Command Reporting System Data

- 1.0 Mission Area Status (Ref. 6, Ref. 12)
- 1.1 Mission Area Subsystem Status (Ref. 6, Ref. 12)
- 1.2 Capability Degraded, That Subsystem
- 1.3 Equipment Degraded
- 1.4 Estimated Time to Repair
- 1.5 Parts Status (if required)

Table A-2 Local Area Terminal Data

2.0 Data keyed by operator and/or retrieved from storage to fill out OPNAV 4790/2-K Fig A-1, NAVSUP form 1250 Fig. A-2, and CASREP Message (Classfied)

Table A-3 Base System Interface Data

R-1051

3.0 Noise Figure

SRC-20

- 4.0 VSWR
- 4.1 Output Power
- 4.2 Modulation
- 4.3 Receiver Sensitivity

Appendix B

The center area of the LAT CRT will display various tables which provide status information. This information may be general or detailed, and refer to the overall status of the equipment or a specific parameter of a particular unit. The displays must provide operators with information that is meaningful and helpful for performing their tasks. Figures B-1 through B-5 show a first cut at the display designs.

Operators will be provided with training and manuals to assist them in reading these displays. However, care has been taken to make the displays as clear and direct as possible. It is expected that some LATs will control three BSIs and so the designs make provisions for a third BSI. The actual tables presented at a LAT will only show BSIs that are controlled by that LAT.

The test report for units monitored by BSI 2 is shown in Figure B-5. Similar test reports will be provided for the units monitored by other BSIs.

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BSI 3R

BSI 2= C1

BST 1 = C2

OVERALL = C2			8	2		9	K	SRC	K	~		-,.
OVERA	1	_		_		<u> </u>			_			
		2	٥	2	<u>u</u>				×			
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SUMMARY		9	9	0	٥	×		×				×
STATUS			BS1 1	25122		R-1051 (1)	R-1051 (2)	R-1051 (3)			R-1051 (6)	

2021	×
7 Y Y	
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0000	××
BSI 2 UNITS	SRC-20(1) SRC-20(2) SRC-20(3) SRC-20(4) SRC-20(4)

2024	
F 4 = 7	
0 < WN	
0000	
BS1 3	

TEST RESULTS CUIDATED 8 INDICATES TESTING NOT PERFORMED NON

FULLHOW KET ALL VNITS THIS TABLE IS BISPLAYED WHEN THE OPERATOR PRESSES THE NOTE:

FIGURE 8-1 OVERAL

OVERALL STATUS SUMMARY

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2

DISPLAY AREA

	R-1051 No						
PROBLEM TYPE	(1)	(2)	(3)	(4)	(5)	(6)	(7)
MEATURENEUT FAILED					×		
MEASUREMENT ERROR	:					!	
MEALURE MENT OUTDATED							
INTERFACE BAD							
OAR IZR							
TESTING LOCKED OUT				×		1	

Note: This table is displayed the First time the operator presses the Problem units punction key. The next time he presses the key a similar table for BSI 2 will be presented, then for BSI 3 and them back to BSI 4.

FIGURE B-2 BSI 1 PROBLEM UNITS DISPLAY

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DISPLAY AREA

א נדגאט	S.E DINC	STAGTU	CURRI	ENT TIM	1410
851	<u> </u>	BS2	2	BEI	3
7[40	TIME	71,40	TIME	UU37	TIME
R-1051 (4)	2501	SRC-20(4)	1435		1
R-1051 (2)	1450		, 5 -		1
	•]]
					1
1		1			1
1					
i					1

UNIT STATUS WILL BE OUTDATED AT SPECIFIED TIME

Note: THIS TABLE IS DISPLAYED WHEN THE UPDATE NEEDED PUNCTION KEY IS PRESSED.

FIGURE B-3 UNITS NEEDING STATUS UPDATE DISPLAY

The second secon

DISPLAY AREA

BSI 1 UNITS	271 KU 271 NU	BSS 3
R-1051 (4) R-1051 (2)	SRC-20 (3) SRC-20 (5)	

NOTE: THIS TABLE IS DISPLAYED WHEN THE LOCKED OUT FUNCTION KEY IS PRESSED.

FIGURE B-4 LOCKED OUT UNITS DISPLAY

CHARLES

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	8	The second

P21 F	SRC-20 (1		TUS E PASS		
PARAM	SUPATE	MEASURED VALVE	FAIL LIMITS	PASS LIMITS	LIMITS
RCVR 3 EUS	Good				
Power Untrut	6000				
Megu- LATION	2249				
VSWR	6000				

NOTE: NORMAL DISPLAY - MEASURED VALUES AND LIMIT VALUES FOR ALL PARAMETERS TESTED WILL BE FILLED IN.

BSI 2 SRC-20 (1) a mensye will appear here

NOTE: ABUDANAL TEST REPORT DISPLAY - A MESSAGE MILL BE PROVIDED STATING THE SITUATION THAT PREVENTED NURMAL TESTING.

EXAMPLES ARE: TESTING LOCKED BYT,

INTERFACE DOWN

Note: This table is presented automatically in response to an action at the LAT to initiate testing of the unit, and when the BSI & Units function key is pressed. Subsequent pressing of the key through displays for the other BSI & units.

FIGURE B-5 TEST REPORT FOR BSI & UNITS

the state of the s

Appendix C

LED Display Characteristics



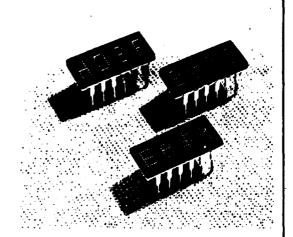
FOUR CHARACTER SOLID STATE ALPHANUMERIC DISPLAY

HDSP-2000

TECHNICAL DATA APRIL 1978

Features

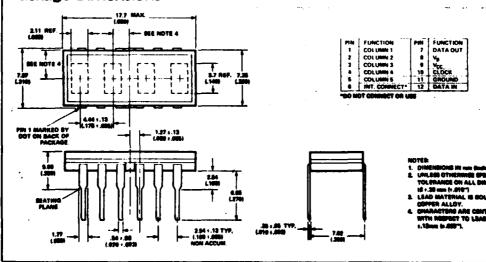
- INTEGRATED SHIFT REGISTERS WITH CONSTANT CURRENT DRIVERS
- CERAMIC 7.62 mm (.3 in.) DIP Integral Red Glass Contrast Filter
- WIDE VIEWING ANGLE
- END STACKABLE 4 CHARACTER PACKAGE
- PIN ECONOMY 12 Pins for 4 Characters
- TTL COMPATIBLE
- 5x7 LED MATRIX DISPLAYS FULL ASCII CODE
- . RUGGED, LONG OPERATING LIFE
- CATEGORIZED FOR LUMINOUS INTENSITY Assures Ease of Package to Package Brightness Matching



Description

The HP HDSP-2000 display is a 3.8mm (0.15 inch) 5x7 LED array for display of alphanumeric information. The device is available in 4 character clusters and is packaged in a 12-pin dual-in-line type package. An on-board SIPO (serial-in-parallel-out) 7 bit shift register associated with each digit controls constant current LED row drivers. Full character display is achieved by external column strobing. The constant current LED drivers are externally programmable and typically capable of sinking 13.5mA peak per diode. Applications include interactive I/O terminals, point of sale equipment, portable telecommunications gear, and hand held equipment requiring alphanumeric displays.

Package Dimensions



Absolute Maximum Ratings

Supply Voltage V _{cc} to Ground	0.5V to 6.0V
Inputs, Data Out and Va	
Column Input Voltage, Viril	- 0.5V to +6.0V
Free Air Operating Temperature	•
Range, TA ⁽²⁾	-20°C to +70°C

Storage Temperature Range, T. -55°C to +100°C Maximum Allowable Package Dissipation Maximum Solder Temperature 1.59mm (.063") Below Seating Plane t<5 secs 260°C

Recommended Operating Conditions

Parameter	Symbol	Min.	Nom.	Mex.	Units
Supply Voltage	Vcc	4.75	5.0	5.25	V
Data Out Current, Low State	luL			1.6	mA
Data Out Current, HighState	lon .			-0.5	mAS
Column Input Voltage, Column On	Vcn	2.6		Vcc	V
Setup Time	lurup	70	45		M
Hold Time	lane.	30	0		ns
Width of Clock	for(Clock)	75			□ ne
Clock Frequency	Crinck	0		3	MHz
Clock Transition Time	t _{ine}			200	ns ns
* Free Air Operating Temperature Range	TA	-20	1	70	·c

Electrical Characteristics Over Operating Temperature Range

(Unless otherwise specified.)

Description		Symbol	Test Conditions	Test Conditions		Typ.	Mex.	Unite
Supply Current		V _{CC} = 5.25V V _{CLOKE} = V _{DAIA} = 2.49		V _H = 0.4V		45	#0	mA
		All SR Stages = V _B = 2.4V	Vp = 2.4V		73	96	mA	
Column Current at any Co	lumn Input	lcor	V _{CC} = V _{COL} = 5.25V All SR Stages = Logical 1	Ve=0.4V			1.5	mA
Column Current at any Co	lumn input	fcoi	Ve=2.4V		336	410	mA	
Pesk Luminous Intensity per LED[3,7] (Character Average)		RPEAR	V _{CC} = 5.0V, V _{CDL} = 3.5V T ₁ = 25°C ⁽⁴⁾ V _B =2.4V		105	200		μCd
Vs. Clock or Data Input Thr	eshold High	Vin	V _{CC} = V _{CHL} = 4.75V		2.0			V
Vs. Clock or Data Input The	eshold Low	Vii					0.8	٧
Input Current Logical 1	Vs. Clock	I _{IH}	W = 5 05M M = 0.4M			20	80	μA
	Data In	l ₁₀₀	$V_{CC} = 5.25V, V_{IM} = 2.4V$			10	40	μA
Input Current Logical D	Va.Clock	111				-600	-800	μA
	Data In	In.	V _{CC} = 5.25V, V _{II.} = 0.4V			-250	-400	μА
Onto Out Voltage		Volt	$V_{CC} = 4.75V$, $I_{OH} = -0.5m$	1, V ₍₁₀₎ = 0V	2.4	3.4		V
Data Out Voltage		Vol	$V_{CC} = 4.75V$, $I_{OL} = 1.6mA$,	V _{COL} = 0V		0.2	0.4	V
Power Dissipation Per Package**		Po	V _{cc} = \$.0V, V _{col.} = 2.6V, 15 LEDs on per character	, Vo = 2.4V		0.08		w
Peak Wavelength		APEAK				655		nm
Dominant Wavelength ¹⁵		λ _d				639		nm

^{*}All typical values specified at $V_{\rm CC}$ = 5.0V and T_A = 25°C unless otherwise noted.

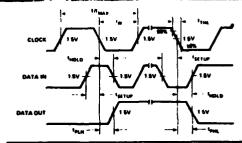
- NOTES: 1 Maximum absolute dissipation is with the device in a socket having a thermal resistance from pins to ambient of 35°C/watt.

 2 The device should be derated linearly above 25°C at 16mW/°C (see Electrical Description on page 3).

 3. The characters are categorized for Luminous Intensity with the intensity category designated by a letter code on the bottom of the
 - 4. T, refers to the initial case temperature of the device immediately prior to the light measurement
 - 5. Dominant wavelength A_d is derived from the CIE chromaticity diagram, and represents the single wavelength which defines the color of the device
 - 6. Maximum allowable dissipation is derived from V_{t} , V_{h} , V_{t+1} , 5.25 Volts, 20 LEDs on per character. 7. The luminous stearance of the LED may be calculated using the following relationships

 - L. (Lux) I. (Candola)/A (Metre)
 - L. (Footlamborts) #1. (Candola)/A (Foot) A 5.3 x 10 M 5.8 x 10 (Foot)

^{**}Power designation per package with 4 characters illuminated.



Parameter	Condition	M	Ě	Max.	Units
L. Mex. CLOCK Rate		3	**		MHZ
Propagation delay CLOCK to DATA OUT	Ct = 15pF Rt=2.4KΩ	10		80	ne.

Figure 1. Switching Characteristics. (V_{CC} = 5V, ... T_A = -20°C to +70°C)

Mechanical and Thermal Considerations

The HDSP-2000 is available in a standard 12 lead ceramicglass dual in-line package. It is designed for plugging into DIP sockets or soldering into PC boards. The packages may be horizontally or vertically stacked for character arrays of any desired size.

The -2000 can be operated over a wide range of temperature and supply voltages. Full power operation at $T_A=25^{\circ}\mathrm{C}$ ($V_{CC}=V_B=V_{CDL}=5.25\mathrm{V}$) is possible by providing a total thermal resistance from the seating plane of the pins to ambient of $35^{\circ}\mathrm{C/W/cluster}$ maximum. For operation above $T_A=25^{\circ}\mathrm{C}$, the maximum device dissipation should be derated above $25^{\circ}\mathrm{C}$ at $16\mathrm{mW/^{\circ}\mathrm{C}}$ (see Figure 2). Power derating can be achieved by either decreasing V_{COL} or decreasing the average drive current through pulse width modulation of V_B .

The -2000 display has an integral contrast enhancement filter in the glass lens. Additional front panel contrast filters may by desirable in most actual display applications. Some suggested filters are Panelgraphic Ruby Red 60, SGL Homalite H100-1605 and Plexiglass 2423. Hewlett-Packard Application Note 964 treats this subject in greater detail.

Post solder cleaning may be accomplished using water, Freon/alcohol mixtures formulated for vapor cleaning processing (up to 2 minutes in vapors at boiling) or Freon/alcohol mixtures formulated for room temperature cleaning. Suggested solvents: Freon TF, Freon TE, Genesoly DI-15. Genesoly DE-15.

Electrical Description

The HDSP-2000 four character alphanumeric display has been designed to allow the user maximum flexibility in interface electronics design. Each four character display module features Data In and Data Out terminals arrayed for easy PC board interconnection such that display strings of up to 80 digits may be driven from a single character generator. Data Out represents the output of the 7th bit of digit number 4 shift register. Shift register clocking occurs on the high to low transition of the Clock input. The like columns of each character in a display cluster are tied to a single pin. Figure 5 is the block diagram for the HDSP-2000. High true data in the shift register enables the output current mirror driver stage associated with each row of LEDs in the 5x7 diode array.

The reference current for the current mirror is generated from the output voltage of the $V_{\rm B}$ input buffer applied across the resistor R. The TTL compatible $V_{\rm B}$ input may either be tied to $V_{\rm CC}$ for maximum display intensity or pulse width modulated to achieve intensity control and reduction in power consumption.

The normal mode of operation is depicted in the block diagram of Figure 6. In this circuit, binary input data for digit 4, column 1 is decoded by the 7 line output ROM and then loaded into the 7 on board shift register locations 1 through 7 through a parallel-in-serial-out shift register. Column 1 data for digits 3, 2 and 1 is similarly decoded and shifted into the display shift register locations. The column 1 input is now enabled for an appropriate period of time, T. A similar process is repeated for columns 2, 3, 4 and 5. If the time necessary to decode and load data into the shift register is t, then with 5 columns, each column of the display is operating at a duty factor of:

$$D.F. = 5(1+T)$$

The time frame, t + T, allotted to each column of the display is generally chosen to provide the maximum duty factor consistent with the minimum refresh rate necessary

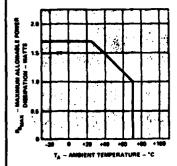


Figure 2. Maximum Allowable Power Dissipation vs. Temperature.

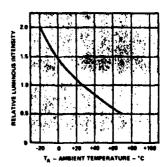


Figure 3. Relative Luminous Intensity vs. Temperature.

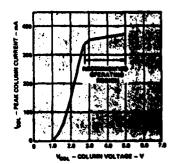


Figure 4. Peak Column Current vs. Column Voltage.

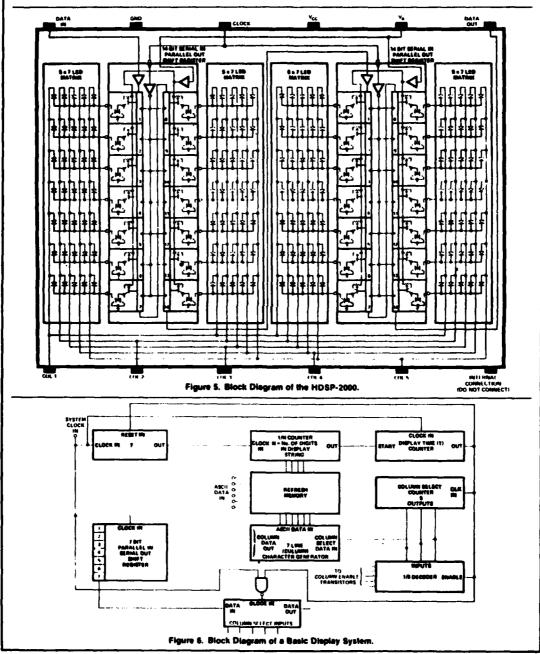
.... * 44 Co.

to achieve a flicker free display. For most strobed display systems, each column of the display should be refreshed (turned on) at a minimum rate of 100 times per second. With 5 columns to be addressed, this refresh rate then gives a value for the time t+T of:

 $1/[5 \times (100)] = 2$ msec.

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If the device is operated at 3.0 MHz clock rate maximum, it is possible to maintain t < T. For short display strings, the duty factor will then approach 20%. For longer display strings operation at column duty factors of less than 10% will still provide adequate display intensity in most applications. For further applications information, refer to HP Application Note 968, Application Bulletin No. 51 and Application Bulletin No. 55.



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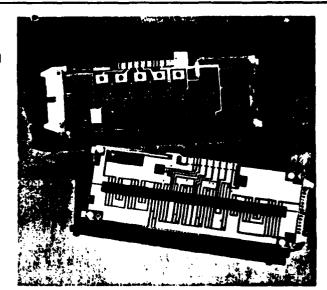
5 x'7 DOT MATRIX ALPHANUMERIC DISPLAY SYSTEM

HDSP - 2416 HDSP - 2424 HDSP - 2432 HDSP - 2440 HDSP - 2470 HDSP - 2471 HDSP - 2472

TENTATIVE DATA SEPTEMBER 1978

Features

- COMPLETE ALPHANUMERIC DISPLAY SYSTEM UTILIZING THE HDSP-2000 DISPLAY
- CHOICE OF 64, 128, OR USER DEFINED ASCII CHARACTER SET
- CHOICE OF 16, 24, 32, or 40 ELEMENT DISPLAY PANEL
- MULTIPLE DATA ENTRY FORMATS Left, Right, RAM, or Block Entry
- EDITING FEATURES THAT INCLUDE CURSOR, BACKSPACE, FORWARDSPACE, INSERT, DELETE, AND CLEAR
- DATA OUTPUT CAPABILITY
- SINGLE 5.0 VOLT POWER SUPPLY
- TTL COMPATIBLE
- EASILY INTERFACED TO A KEYBOARD OR A MICROPROCESSOR



Description

The HDSP-24XX series of alphanumeric display systems provides the user with a completely supported 5 x 7 dot matrix display panel. These products free the user's system from display maintenance and minimize the interaction normally required for alphanumeric displays. Each alphanumeric display system is composed of two component parts:

- An alphanumeric display controller which consists of a preprogrammed microprocessor plus associated logic, which provides decode, memory, and drive signals necessary to properly interface a user's system to an HDSP-2000 display. In addition to these basic display support operations, the controller accepts data in any of four data entry formats and incorporates several powerful editing routines.
- 2. A display panel which consists of HDSP-2000 displays matched for luminous intensity and mounted on a P.C. board designed to have low thermal resistance.

These alphanumeric display systems are attractive for applications such as data entry terminals, instrumentation, electronic typewriters, and other products which require an easy to use 5 x 7 dot matrix alphanumeric display system.

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S. 19.5

P	PART NUMBER		DE	SCRIPTIO	N	
	Display Boar	ds				
ſ	HDSP-2416	Single-line utilizing the				penel
	HDSP-2424	Single-line utilizing the				penel
Ì	HDSP-2432	Single-line utilizing the				penel
Ì	HDSP-2440	Single-line utilizing the				penel
	Controller B	oerde				

HDSP-2470	HDSP-2000 display interface incorporating a 64 character ASCII decoder
HDSP-2471	HDSP-2000 display interface incorporating a 128 character ASCII decoder
HDSP-2472	HDSP-2000 display interface without ASCII decoder. Instead, a 24 pin societ is provided to accept a custom 126 character set from a user programmed 1K x 8 PROM.

When ordering, specify one each of the Controller Board and the Display Board for each complete system.

HDSP-2416/-2424/-2432/-2440

Absolute Maximum Ratings

Supply Voltage Vcc to Ground	0.5V to 6.0V
Inputs, Data Out and Va	0.5V to Vcc
Column Input Voltage, VCOL	-0.5V to +6.0V
Free Air Operating Temperature	
Range, Ta ^[1]	0°C to +55°C
Storage Temperature Pance To -5	5°C 10 1100°C

Recommended Operating Conditions

Parameter	Symbol	Min.	Norm.	Mex.	Units
Supply Voltage	Vcc	4.75	5.0	5.25	٧
Column Input Voltage, Column On	VCOL	2.6			>
Setup Time	tsetup	70	45		ns
Hold Time	THOLD	30	0		ns.
Width of Clock	tw(CLOCK)	75			NS.
Clock Frequency	fcLOCK	0		3	MHz
Clock Transition Time	tTHL			200	ns
Free Air Operating ^[1] Temperature Range	TA	0		55	•c

Electrical Characteristics Over Operating Temperature Range

(Unless otherwise specified)

Parameter	Parameter		Min.	Typ.*	Max.	Units	Condition	18
Supply Current				45n	60n ^[2]	mA		VB = 0.4V
		Icc		73n	95n	mA	VCLOCK=VDATA=2.4V All SR Stages = Logical 1	V _B = 2.4V
Column Current at any Column Input		ICOL			1.5n	mA	Vcc = Vcol = 5.25V All SR Stages =	Vg = 0.4V
		Icor		335n	410n	mA	Logical 1	V _B = 2.4V
Peak Luminous Intensity per LED (Character Average)		IV PEAK	105	200		μcd	$V_{CC} = 5.0V, V_{COL} = 3$ $T_j = 25^{\circ} C^{(3)}, V_B = 2.$	
V _B ,Clock or Data Input T	hreshold High	ViH	2.0			• V	V V 4 75V	
Vs. Clock or Data Input 1	hreshold Low	VIL			0.8	V	VCC = VCOL = 4.75V	
Input Current Logical 1	Vs, Clock	lін			80	μА	V 5 05V V 0	414
	Data in	IIH			40	μА	V _{CC} = 5.25V, V _{IH} = 2	.4V
Input Current Logical 0	Vs. Clock	leL		-500	-800	μА	V	414
Data in		leL		-250	-400	μА	Vcc = 5.25V, V _{IL} = 0.4V	
Power Dissipation Per Board ^[4]		PD		0.66n		W	V _{CC} = 5.0V, V _{COL} = 5 15 LED's on per Char V _B = 2.4V	

^{*}All typical values specified at Vcc = 5.0V and T_A = 25°C unless otherwise noted.

NOTES

- 1. Operation above 55°C (70°C MAX) may be achieved by the use of forced air (150 fpm normal to component side of HDSP-247X controller board at sea level).
- 2. n = number of HDSP-2000 packages

HDSP-2416 n = 4

HDSP-2424 n = 6

HD8P-2432 n = 8

HDSP-2440 n = 10

- 3. Tj refers to initial case temperature immediately prior to the light measurement.
- 4. Power dissipation with all characters illuminated.

If D7 is a logic low when the DATA IN lines are read, the controller will interpret D6-D6 as standard ASCII data to be stored, decoded and displayed. The system accepts seven bit ASCII for all three versions. However, the HDSP-2470 system displays only the 64 character subset |2016

(space) to 5F16 (4) and ignores all ASCII characters outside this subset with the exception of those characters defined as display commands. These display commands are shown in Figure 5. Displayed character sets for the HDSP-2470/-2471 systems are shown in Figure 6.

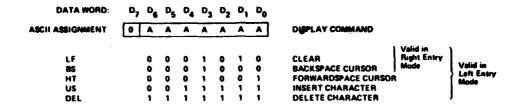
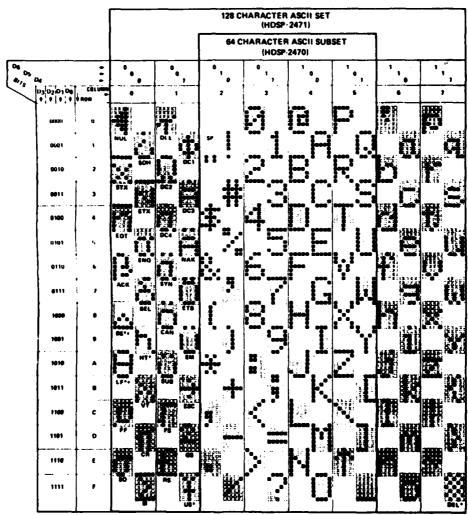


Figure 5. Display Commands for the HDSP-2470/-2471/-2472 Alphanumeric Display Controller.



*DISPLAY COMMANDS WHEN USED IN LEFT ENTRY
*DISPLAY COMMANDS WHEN USED IN RIGHT ENTRY

Figure 6. Display Font for the HDSP-2470 (64 Character ASCII Subset), and HDSP-2471 (128 Character ASCII Set) Alphanumeric Display Controller.

Appendix D

This appendix provides a list (Table D-1) for checking the design characteristics against human engineering design criteria set forth in MIL-STD-1472B. The list is only partially complete. This report does not provide all the details of the system design and therefore it cannot provide for a complete evaluation of the design against MIL-STD-1472B. It is the intent of this appendix to illustrate how the list has been used for evaluating the design features described in this report, and how it will be used to evaluate the other design characteristics as they are established. A check () on the list indicates compliance, a 0 indicates a discrepancy, and an NA indicates not applicable. The first page of the list goes through MIL-STD-1472B paragraph by paragraph as would be done before acceptance of the overall design. The second page selects paragraphs that pertain to design features included in this report.

ANCE D-1	M3L - S*	FD- 147	72 B	CHECK-OFF !	L187 (su	ees lor
MILT STD-1472B Paragraph	LAT	BSI	-, l	MIL-STO-14728 PARAGRAPH S	LAT	BSIS
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5.1.1.2 5,1.1.3	<u> </u>	V		5.2.1.2.8	-1	
5.1.1.1	~	V		5,21,3,8		
5.1.1.5	· V	V		5.2.1.3.3		
5.1. 2.1 .1 (1) 5.1. 2.1 .1 .1	NY NY	0		5.2.1.3.5		
5.1.2.1.1.2	1	1		5. 2, 1, 3.6		
5. 1. 2. 1. 1. 3	NA			5.2. 1. 3.7	. V .	
5.1. 2.1. 1. 4 5.1. 2. 2	AN NA	NA	-	5.2.1.3.9	NA	- NA
5.1.2.3	NA	V		5, 2, 1, 3, 10		
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5.1. 2. 3.6	NA	hV VV		5. 2. 2. 1. 3	NA NA	
5.1.2 5.1.4	NA	NA		5.2.2.1.4	NA .	
5.2.1	'		ļ <u>.</u>	5.2.2.1.5	MA	NA
5. 2. 1. <i>1</i> 5. 2. 1. 2. 1				5.2.2.1.6	L VA	VA
5.2.1.2.2	V	1	<u></u>	5.2.2.1.8	NA .	V
5, 8, 1, 2, 3				5. 2. 2. 1,4	NA	
5, 2, 1, 2, 4				5.2.2.1.10	NV.	NA
5, 2, 1, 2, 5 5, 2, 1, 2, 6	V			5.2.2. 1.12	Au	MA
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A Problems

Appendix E

MIL-STD-12C, Abbreviations for Use on

Drawings, Specifications, Standards and in Technical Documents

(excerpts)

YERMA	ERM ASSREVIATION		TERM	ABBREYIATION		
radio direction			raw tape write			
finding	RDF	rď	submodule RT	W8	rtws	
radio frequency	RF	ri	raw water	7	I.M.	
radio frequency			rawhide	MHD	rwhd	
amplification by			rayon	'n	ryn	
stimulated emission			rayon (insul) RA		ra .	
of radiation	RASER	FASSI	reactance RE	AC	reac	
radio-frequency choke		ric	reaction	TN	rctn	
radio-frequency			reactivate RE	ACTVT	reactvt	
interference	RFI	rli	reactive factor			
radio interference			meter	M	rfm	
field intensity	RIFI	rifi	reactive volt-			
radio operator	RAD OPR	rad opr	ampere meter RV	'Α	IVA	
radio teletypewriter	RTTY	rtty	reactor	AC	reac	
radioactive	RAACT	raact	reactor compartmentRC		rc	
radioactive			reactor core RC	: 0	TCO	
liquid waste	RALW	ralw	readRD	•	rd	
*radiographic			read-write (head)	W	I-M	
inspection	RAD INSP	rad insp	readerRI	NR .	rdr	
radiological		radl	reader common			
radiological			contact RC	:C	rec	
defense	RADDEF	raddef	reader tape			
radiological			contact	rc .	rtc	
warfare	RADWAR	RADWAR	readiness	ns	rdns	
radius		rad	reading RD	NG	rdng	
*rail		r	readout	OUT	rdout	
railing		rle	readout and relay	R	r/r	
railroad		rr	ready		rdv	
railway		ry	ready service RS		rs .	
raintight		rt	real and not-			
rainwater			corrected			
conductor	RWC	rwc	input data	NCID	rancid	
*raised		red	real time		rt	
raised face		rí	real-time input-			
raised face diameter		rfd	output transducer Ri	OT	riot	
raised face height	RFH	rfh	reamer Rk	-	rmr	
ramjet	RMJ	rmi	rear connection		rc	
random		rndm	rear view		IA	
random access			*reassemble RE	CASSEM	reassem	
discrete address			rebabbit RI	BT	rbbt	
system	RADAS	radas	recalculated		recalc	
range		rng	recall		rel	
range height	_	•	receive		LCA	
indicator	RHI	rhi	receive-only tape	-		
range light		ra lt	perforatorRO	TR	rotr	
range marks		rm	*received		rcvd	_1_1
range rate indicator		rri	-receiver RC		LCAL	П
rapid rectilinear		PF	receiver-			77
*ratchet		rcht	transmitter	7	rt	U
rate		rt	receiving RC		LCAE	_
rate of change		PC	*receptacle RC		rept	
rateau	_	rat	*reception		reptn	
rating		rte	recess	_	rec	
ratio		7	recessed		Lec	
rattail		rttl	recharger	_	rechre	
raw material		rm	reciprocating		recip	
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^{*}Abbreviation changed

	TERM	ABBRE	MOITAIV	TERM	ASSREVIATION	
	sensesense amplifiersensitivesens	sen Sa Sens	sen sa sens	shearingsheathingsheave	SHRNG SHTHG SHV	shrng shthg shv
Π^{-}	-sensitivity	SENS_	sens	sheet	SH .	sh .
	sensitivity time			sheeting	SH SHL	sh shi
	control	STC	stc	shell	8D	ad .
	sensitizedsensitized material	SNTZD	satzd	shell destroying	SHL	ah)
	print	SMP	smp	shield	SHLD	shid
	sensitizing	SNT2G	antzg	shield .		
	sensor	SNSR	80.67	(electron device)	SH	89
	separate	SEP	sep	shielding	SHLD	shid
	separator	SEP	sep	shift	SHF	shí
	sequence	SEQ	seq	shift register	SR .	8F
	sequence check	SEQ CHK	seq chk	ship class	SHPCL	shpcl
	sequential coding	SECO	Seco	ship control	SCONT	SCOUL
	serial	SER	ser	ship course	SCOU SDIS	adis
	serial number	SERNO	serno	ship distance	ODIO	
	series	SER	ser	Ship Draft Indicating System	SDES	SDIS
	*series relay	SRLY SERR	srly serr	ship draft indicator		
	serrate	SERR	serr Serr	transmitter	SDIT	adit
	*service	SVCE	svce	Ship Inertial		
	service bulletin	SB	sb	Navigational System	SINS	SINS
	service ceiling	SRVCLG	srvclg	ship parts		
	service fuel oil	SFO	sio	control center	SPCC	spec
	service sink	SS	88	ship service	86	68
	service, sort and			ship service		4
	merge	SESAME	sesame	turbo generator	SSTG	setg
	serving	SERG	serg	ship speed	85P	sep
	servo	svo	870	ship status	SHSTS	shets shobd
	servomechanism	SERVO	servo	shipboard	SHPBD	supou
	servomotor	SVMTR	svintr sscr	shipboard allowance	SAL	sal
	* setscrew	SSCR SETR	setr	shipfitter	SFTR	aftr
	setter	SET	set	shipment	SHPT	shot
	*setting	SETLG	setlg	shipping	SHPNG	shong
	seven conductor	7/C	7/c	shipping container	SHCR	sher
	sewage	SEW	sew	shock absorber	SH ABS	sh abs
	sewer	SEW	sew	shoemaker	SHMKR	shmkr
	sexless (conductor)	SXL	sxl ,	shop missile assembly		
	sextant	SXTN	sxtn	and maintenance	8M8A	smsa
	shackle	SH	sh	shop order	80	80
	shaft	SFT	sft	*shore connection	SH CONN	sh conn
	shaft alley	SA	82	shore terminal box	STB	etb
	shaft center	SC	8 C	shoreline	SHLN	shin short
	shaft extension	SFT EXT	sft ext	short circuit	SHORT SCR	BUDIL
	shaft gear		shftgr	short-circuit ratio	oc n	
	shaft horsepower		shp shori	short leaf yellow	SLYP	slyp
	shakeproof		shk	short range	E	
	shape		sho	navigation	SHORAN	shoran
	shaped charge		SC.	short side	SHTSD	shted
	share	= -	sh	short takeoff and		
	sharpener		shrp	landing	STOL	STOL
	shear plate		sp	short taper	STPR	stpr
			-	-		

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^{*}Abbreviation changed

TERM	ABBREV	ATION	TERM	ABSRET	MATION	
very high frequency			voltage detector	VDET	vdet	
omnidirectional and			voltage drop		vd	
radio range	VOR	VOR	voltage regulator		VF	
very long range		vlr	•voltage relay	VRLY	vrly	
very low akitude		via	-voltage standing wave			
very low frequency	VLF	V II	ratio	VSWR	VSW1	
very short takeoff and			voltage-tunable	******		
landing		VSTOL	magnetron		ytm.	
vestibule		vest	voltammeter		VAIN VIII	
vestigal sideband vestigal sideband	V GIS	Asp	voltmeter switch		VS.	
modulation	VRM	vam	volume		vol	
vibrate		Aip	volume indicator		vi.	
vibration		vib	volume of compartment .		VC.	
Vickers hardness		Vh	volume unit		₹ U	
video		vid	volumetric	VLMTRC	vimtre	
video amplifier	VIDAMP	vidamp	volute		vi t	
*video frequency	VIDF	vidi	•vulcanize		Arific	
video integration	VINT	VINT	*waier		wir	
village		Aij	wagon		WAE	
violet		vio	wagon box		wb wa	
viscometer		vismr	wainscot		wig	
viscosity		visc vi	•wake light		wk lt	
viscosity index		vsbl	wall board		wib	
visual	VIS	vis	wall hydrant		wh.	
*visual aural radio range	VARR	ASLL	wall receptacle		WI	
visual flight rules		VFR	wall vent		WY	
visual identification		visid	walseal	WLSL	wisi	
vital load center	VLC	v lc	wanigan		Wan	
vitreous		v it	wardrobe		MLP	
vitrified clay		AC	wardroom		W	
vitrified clay tile		vct	warehouse		whee warbd	
voice	VO	₩0	warheadwarming		WILLIAM	
voice actuated trans-			warning		WIR	
mitter keyer inhibitor	ANTIVOY	ANTI VOX	warping		WIPE	
voice coil	AC	VC	warranty		Warr	
voice frequency		νί	wash bucket		wb	
voice-operated device	•-	••	wash fountain	WF	wi	
for automatic			Washburn and Moen			
transmission	VODAT	vodat	Gage		MFM CV	
voice operated			•washer		wehr	
transmitter keyer		vox	washing		wahg	
voice tube		vt	washroom		W	
void	, V D	vd	waste		WP	
volt, alternating	VAC	Vac	waste stack		WS	
volt. direct current		Vdc	water		wtr	
volt ohm milliammeter		AOLD	water chiller		wehr	
voltage		V	water closet		WC	
voltage adjusting		-	water-cooled		weld	
rhecatat	V ADJ R	v adj r	water heater	WH	App.	
voltage control transfer	. VCT	vct	water jacket		wj	
voltage controlled			water line		wi	
oscillator	, VCO	YCO	water meter	WM	WID	

^{*}Abbreviation changed

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	ABBREVIATION		TERM	ABBREVIATION		TERM	
	NITSTL NK		mitride steel	NRCP	nrcp	nonreinforced concrete	
	NKL	nk nkl				pipe	
	NL CHG		normal charge	NRD NRETN	nrd	nonreplexishable demand	
	NL LT		net-laying light	NRL NRL	nretn	non-return	
	NLG		nose landing gear	NRVSBL	nri nrvsbi	night ration locker nonreversible	
	NLNR	ninr		NRZ	nrs	non-return-to-sero	
	NLT		normal lube oil tank				
	NM	nm	noise meter	ns	NS	National special (thread) near side	
	NM	nm	nonmetallic	ns Ns	ns	nickel steel	
	NM	nm	nuclear magnetron	ns NSLF	nsif	nonself	
	NMAG	_	nonmagnetic	NSS	NSS	Navy Secondary Standards	
Ц_	NO		normally open	nst	nst	nonslip tread	
Ц_	NO	no		NT	mt	navy type	
11	NOCCC		no control circuit contacts	NT	mt	nontight	
—	NOG	nog		NTC	ntc	negative temperature	
	NOL NOM		normal overload			coefficient	
	NOM NOMAD	nom	naval oceanographic	NTN	ntn	neutron	
	NOMIND	попнас	meteorological	NTP	ntp	normal temperature and	
			automatic device			pressure	
	NOMEN	nomen	nomenciature	NTPL	ntpl	nut plate	
	NONFLMB		nonflammable	nts	nts	negative torque signal	
	NONSTD		nonstandard	NTS	nts	not to scale	
	NONSYN		nonsynchronous	NTWK	ntwk	network	
	NOP		number of passes	NTWT	ntwt	net weight	
	NORM	norm		NUC	nuc	nuclear	
	NORM	norm	normalize	NUM	num	numeral numerical	
	NOSC	nosc	nonoscillating	NUM NVR	num DVF	no voltage release	
	NOZ	noz	nozzie	NWG	NWG	National Wire Gage	
	NP		National pipe	NWT	nwt	nonwatertight	
	NP		nickel plated	NYL	nyl	nylon	
	NP		nonprocurable	0 70 0	•	•	
	NP	•	nonpropelled	O&R	o to o	out to out	
	NPA	npa		O&S	o&r	overhaul and repair	
	NPET		nonpetroleum	O/M	o&s	otherwise specified outside of metal	
	NPL	npl	•	O/P	o/p	cealid print	
	NPN	npn	negative-positive-	OA OA	02	over-all	
			negative (transistor)	OAO	OAO	orbiting astronomical	
	NPRN	nprn	neoprene			observatory	
	NPS	NPS	Navy Primary Standards	OBA	oba	oxygen breathing	
	NPSC	NPSC	straight thread (pipe			apparatus	
	NPSF	NPSF	couplings) thread for press tight	OBE	obe	outerback end	
	MPSF	NPSF	joints	OBJ	obj	object	
	NPSH	npsh	and nipples	OBJV	objv	objective .	
	NPSL	NPSL	locknut pipe thread	OBL	obl	oblique	
	NPSM	npsm	ioints	OBRNR	obrar	oil burner	
	NPT	NPT	National taper pipe	OBS	obs	opeeine	
		=	(thread)	OBS	obs	obsolete	
	NPTF	npti	tight joints	OBSTN	obstn	obstruction	
	NPTR	NPTR	taper pipe thread	OBSV OBV	obsv	observation	
			(railing fixtures)	OBV	obv	obverse	
	NR	nr	nonreactive (relay)	OC OBW	obw	observation window	
	NR	nr	nuclear reactor		oc	on center	

MOITAIVERERA		TERM	ABBREVIATION		TERM	
FOB	始	front of dash field dynamic braking forced-draft blower	FHT FHY FIC	fhy	fully heat-treated fire hydrant frequency interference	
PDC PDC	ide	feedback fire-department connection	FIG FIL	fig	figure	廿
fde fdfl	fde	field decelerator	FIL FIL	al	fillet	Ц
PDI PDM	1di 1dm	field discharge frequency division	Filh Filh	fil	fuel injection line fillister head	
FDN FDP	fdn	multiplex foundation full dog point	fill fip fir	fip fip	fuel injection pump	
FDPL FDR FDR	维		FIR FIR	fir	fuel indicator reading full indicator reading	
FDR FDRY	fdr fdr fdry	fire door	PK PKD PL	fied	forked	
FDW FDWL FEB		feed water fiberboard, double wall functional electronic	FL FL FL	n n	flood (vent)	
FED	Ped	block Federal	FL FL	n	floor line flow	
Pelr Pelr Pem	feir feir fem	feeler	FL FL FL	n n	flush	
FER CON FET	fer con	forward engine room ferrule-contact	FL FL/W	Ω Ω/w	focal length flash welding	
PEXT PF	fext ff		FLD FLDG FLDK	fldg	folding	
77 77 77	u u	flip flop	FLDNG FLDO FLDT	fldng	flooding final limit, down	
PP PPAR	ff	full field folding fin aircraft	FLEA FLEX	flex	flux logic element array flexible	
FFC FFD		rocket flip flop complementary field forcing (decreasing)	FLEX FLF FLG	flex	final limit, forward	
PFI PFILE PFL	www	field forcing (increasing) flat fillister head female flared	FLG FLGSTF	fig	flooring flagstaff	
PPL PPL	<u>m</u>	field failure flip flop latch	Plgstn Plh Plh	figstn fih	final limit, hoist	
PFL PG PG		front focal length filament ground frog	Flhls Fliden Flkd	fihls	flight data entry	
PGD PGR	igi igr	forged finger	FLL FLL	n	final limit, lower flow line	
PE PR PRC	fi fine		PLLD PLM PLMB	fild fim fimb	flame	
PEP PEP PER	Ap	fractional horsepower friction horsepower fire-hose rack	FLMPRF FLMPRS FLMSD	fimpri	flameproof film processing	

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